

- **Non-contacting inductive technology to eliminate wear**
- **Angle set to customer's requirement**
- **Compact, durable and reliable**
- **High accuracy and stability**
- **Sealing to IP68 10 Bar and IP69K**
- **316 stainless construction**



As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, Positek® has the expertise to supply a sensor to suit a wide variety of applications.

Our S508 RIPS® (Rotary Inductive Position Sensor) is an affordable, durable, high-accuracy rotary sensor designed for industrial, vehicle, marine and offshore applications where sealing from water jets and submersion are complimented with a 316 stainless construction.

The S508, like all Positek® sensors, is supplied with the output calibrated to the angle required by the customer up to a maximum of 160 degrees and with full EMC protection built in. The sensor provides a linear output proportional with input shaft rotation. There is a machined registration mark to identify the calibrated mid point.

It is particularly suitable for OEMs seeking good sensor performance for arduous applications such as industrial machinery where cost is important.

Overall performance, repeatability and stability are outstanding over a wide temperature range. The S508 has long service life and environmental resistance with a rugged stainless steel body. It also offers a range of mechanical and electrical options.

SPECIFICATION

Dimensions

Body diameter	35 mm
Body Length (to seal face)	51 mm standard, 56 mm buffered
Shaft	12.5 mm Ø 6 mm

For full mechanical details see drawing S508-11

Independent Linearity

≤ ± 0.25% FSO @ 20°C - up to 100°

≤ ± 0.1% FSO @ 20°C* available upon request.

*Sensors with calibrated travel up to 100°.

Temperature Coefficients

< ± 0.01%/°C Gain &

< ± 0.01%FS/°C Offset

> 10 kHz (-3dB)

> 300 Hz (-3dB) 2 wire 4 to 20 mA

Frequency response

Infinite

< 0.02% FSO

< 20 mNm Static

Resolution

Noise

Torque

Environmental Temperature Limits

Operating -40°C to +125°C standard

-20°C to +85°C buffered

-40°C to +125°C

Storage

Sealing

IP68 10Bar IP69K

EMC Performance

EN 61000-6-2, EN 61000-6-3

Vibration

IEC 68-2-6: 10 g

IEC 68-2-29: 40 g

Shock

350,000 hrs 40°C Gf

MTBF

Drawing List

S508-11

Sensor Outline

Drawings, in AutoCAD® dwg or dxf format, available on request.

Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs - please contact us with your requirements.

How Positek's PIPS® technology eliminates wear for longer life

Positek's **PIPS®** technology (Positek Inductive Position Sensor) is a major advance in displacement sensor design. PIPS®-based displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

PIPS® technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. A PIPS® sensor, based on simple inductive coils using Positek's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

PIPS® overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials. It requires no separate signal conditioning.

Our LIPS® range are linear sensors, while RIPS® are rotary units and TIPS® are for detecting tilt position. Ask us for a full technical explanation of PIPS® technology.

We also offer a range of ATEX-qualified intrinsically-safe sensors.

TABLE OF OPTIONS

CALIBRATED TRAVEL: Factory-set to measure any angle up to 160°

Full 360° Mechanical rotation.

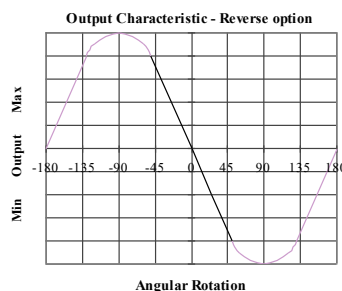
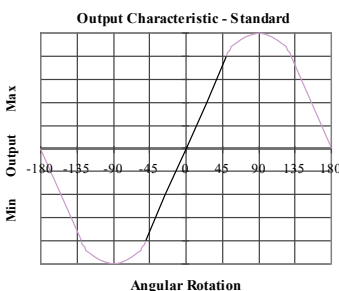
ELECTRICAL INTERFACE OPTIONS

OUTPUT SIGNAL	SUPPLY INPUT	OUTPUT LOAD
Standard: 0.5-4.5V dc ratiometric	+5V dc nom. ± 0.5V.	5kΩ min.
Buffered: 0.5-4.5V dc	+24V dc nom. + 9-28V.	5kΩ min.
±5V dc	±15V dc nom. ± 9-28V.	5kΩ min.
0.5-9.5V dc	+24V dc nom. + 13-28V.	5kΩ min.
±10V dc	±15 V dc nom. ± 13.5-28V.	5kΩ min.
Supply Current	10mA typical, 20mA maximum.	
4-20mA (2 wire)	+24 V dc nom. + 18-28V.	300Ω @ 24V.
(3 wire sink)	+24 V dc nom. + 13-28V.	950Ω @ 24V.
(3 wire source)	+24 V dc nom. + 13-28V.	300Ω max.

CONNECTIONS

Cable with Pg7 gland IP68 10 Bar IP69K

Cable length >50 cm – please specify length in cm



a

b

c

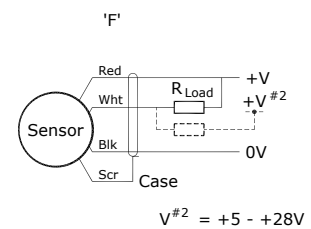
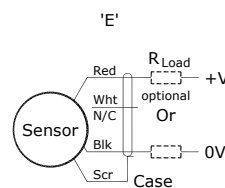
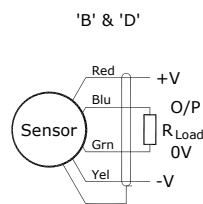
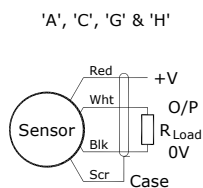
d

S508 . Displacement Output Connections Z-code

a Displacement (degrees)		Value
Displacement in degrees	e.g. 0 - 54 degrees	54
b Output		
Supply V dc V _s (tolerance)	Output	Code
+5V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	A
±15V nom. (±9 - 28V)	±5V	B
+24V nom. (13 - 28V)	0.5 - 9.5V	C
±15V nom. (±13.5 - 28V)	±10V	D
+24V nom. (18 - 28V)	4 - 20mA 2 wire	E
+24V nom. (13 - 28V)	4 - 20mA 3 wire Sink	F
+24V nom. (9 - 28V)	0.5 - 4.5V	G
+24V nom. (13 - 28V)	4 - 20mA 3 wire Source	H
c Connections Cable* or Connector		Code
Cable Gland	IP68 10Bar / IP69K Pg7	Lxx
*Supplied with 50 cm as standard, specify required cable length specified in cm. e.g. L2000 specifies cable gland with 20 metres of cable. Nb: restricted cable pull strength.		
d Z-code		Code
≤± 0.1% @20°C Independent Linearity displacement up to 100 degrees only!		Z650

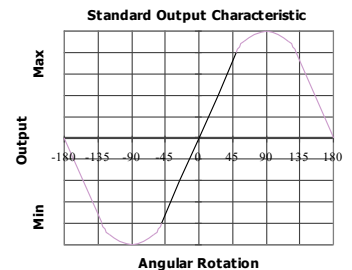
Installation Information

Output Option	Output Description:	Supply Voltage: V_s (tolerance)	Load resistance: (include leads for 4 to 20mA O/Ps)
A	0.5 - 4.5V (ratiometric with supply)	+5V (4.5 - 5.5V)	$\geq 5k\Omega$
B	$\pm 5V$	$\pm 15V$ nom. ($\pm 9 - 28V$)	$\geq 5k\Omega$
C	0.5 - 9.5V	+24V nom. (13 - 28V)	$\geq 5k\Omega$
D	$\pm 10V$	$\pm 15V$ nom. ($\pm 13.5 - 28V$)	$\geq 5k\Omega$
E	4 - 20mA 2 wire Current Loop	+24V nom. (18 - 28V)	$\approx 0 - 300\Omega$ max. @24V ~ 1.2 to 6V across 300Ω $\{R_L \text{ max.} = (V_s - 18) / 20^{-3}\}$
F	4 - 20mA 3 wire Sink	+24V nom. (13 - 28V)	$\approx 0 - 950\Omega$ max. @24V ~ 3.8 to 19V across 950Ω $\{R_L \text{ max.} = (V_s - 5) / 20^{-3}\}$
G	0.5 - 4.5V	+24V nom. (9 - 28V)	$\geq 5k\Omega$
H	4 - 20mA 3 wire Source	+24V nom. (13 - 28V)	$\approx 0 - 300\Omega$ max. ~ 1.2 to 6V across 300Ω



Mechanical Mounting: The flange slots are 4.5mm by 30 degrees wide on a 48mm pitch, sensor is supplied with a 24x2 N70 O-ring face seal. The sensor should be mounted with minimal axial and radial loading on the shaft for optimum life. It is recommended that the shaft is coupled to the drive using a flexible coupling. Tests indicate that life in excess of 16 million cycles can be achieved with 1kg side and end load.

Output Characteristic: The sensor has full rotational freedom and two sectors, 180° apart, over which linear response can be achieved. At the mid point of the calibrated range the output signal will be half full scale deflection, and the flat on the shaft is aligned with the registration mark in the base of the sensor. In the calibrated range the output increases as the shaft is rotated in an anti-clockwise direction viewed from the shaft. The calibrated output is factory set to be between 16 and 160°.



Incorrect Connection Protection levels:-

- A **Not protected** – the sensor is **not** protected against either reverse polarity or over-voltage. The risk of damage should be minimal where the supply current is limited to less than 50mA.
- B & D Supply leads diode protected. Output must not be taken outside $\pm 12V$.
- C & G Supply leads diode protected. Output must not be taken outside 0 to 12V.
- E, F & H Protected against any misconnection within the rated voltage.